

Wind Drift Currents from Remote Sensing

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 $\mathbf{u}_{\text{Stokes}} = a^2 \omega^3 g^{-1} \exp(2kz) \mathbf{e}_{\text{wave}}, \quad \vec{u}_{ek}(z) = \beta(z) \vec{\tau} e^{i\theta(z)}$



Ratio of Stokes Drift to Geostrophic Currents



Ratio of climatological surface Stokes drift speed over climatological surface geostrophic speed. The scale is logarithmic. The Stokes drift is calculated from spectra of ECMWF ERA-40 reanalysis and averaged over 45 years. The geostrophic currents come from a 15-year average of altimeter and in situ observations from AVISO (Carrasco et al, Ocean Dynamics, 2014)

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Advection of Surface Passive Tracers (aka, garbage)



Distributions of virtual surface particles, after 10 years starting from a uniform distribution. The four panels show the effect of three components of the surface current combined or their effect taken separately (Adapted from Onink et al., 2019)



DopplerScatt provides wind **stress** and volicity directions & wind speed.

Coincident data over different wind conditions with HF Radar & ROCIS





What velocity is measured?





 $\mathbf{U}_{\mathrm{M}} = \mathbf{U}_{\mathrm{E}}$

$$\omega = \sqrt{gk} + \mathbf{k} \cdot \mathbf{U}_s$$

 $\mathbf{U}_{\mathrm{M}} = \mathbf{U}_{\mathrm{E}} + \mathbf{U}_{\mathrm{Sf}}$ HF Radar (Ardhuin et al., 2009)

 $U_{\rm M} = U_{\rm E} + U_{\rm S}/2$ DopplerScatt (Rodriguez et al., 2018)

ROCIS (Anderson et al., 2015)

Measured Eulerian velocity is average over the wavelength of the waves used

$$\mathbf{U}_E = 2k_B \mathbf{e}_{\theta_B} \cdot \int_{-\infty}^{0} \hat{\mathbf{u}} \exp(2k_B z) \, dz \quad \text{Stewart & Joy, 1974}$$

HF radar (5 MHz): ~2m depth HF radar (12.5 MHz): ~1m depth ROCIS: ~1m - 2m DopplerScatt: <1mm _{© 2018 California Institute of Technology. Government sponsorship acknowledged.}



DopplerScatt Quantum Eddy Validation





Velocity Differences



CGMF: Wind Drift Uncorrected



Problem Traced to Current GMF Correction Included Wind Drift





Velocity Differences



CGMF: Wind Drift Corrected



DopplerScatt – ROCIS Comparison



Data collection funded by Chevron. ROCIS data courtesy of Areté Associates.

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e CODE drifter velocities, with HF radar velocity magnitude 85.7% (±8.91) that of the ters, directed 9.9° clockwise. Dhile Racarcates in Drifters: Drogued at ints differences of bin-averaged currents from drift Difference of the scatter plots in Figure 7) presentativeness of bin-averaged currents from drift Difference of the between the HF radar in these statistics (as shown by error bars in Figure 8 and listed on each plot of Figure 7). The analysis shows systematically growing significant differences between the HF radar I the Lagrangian velocity measured by drifters at diminishing depths below the surface.



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Effects of Stratification



Figure 1. Velocity profiles from the model. \hat{u} is the downwind quasi-Eulerian velocity, \hat{v} is the crosswind quasi-Eulerian velocity, and U_s is the Stokes drift. Velocities and elevation are normalized by the waterside friction velocity u_* and by the significant wave height H_s , respectively. Solid lines and dashed lines are model results with and without the Stokes-Coriolis effect, respectively. (top) With a 20-m-deep mixed layer as observed during SMILE. (bottom) Without the effect of stratification.

Drift and mixing under the ocean surface revisited: Stratified conditions and model-data comparisons

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Current Shear from Measurements



⁸Passive Optical Sensing of the Near-Surface Wind-Driven Current Profile

NATHAN J. M. LAXAGUE, BRIAN K. HAUS, DAVID G. ORTIZ-SUSLOW, CONOR J. SMITH, GUILLAUME NOVELLI, HANJING DAI, TAMAY ÖZGÖKMEN, AND HANS C. GRABER

FIG. 11. The time-averaged current profile for MCR-1. (bottom) Full derived profile and (top) an expansion of the upper 0.1 m of the profile. Data presented include current observations from the polarimetric wave slope sensing method (•) and the moored ADCP (•). Each symbol's fill color corresponds to its direction (deg) clockwise from true north in an oceanographic going-to convention. Wind velocity direction: 12.74°, wind velocity magnitude: 9.14 m s⁻¹; wind stress direction: 351.85°, wind stress magnitude: 0.0508 N m⁻².

FIG. 13. The time-averaged current profile for MCR-2. (bottom) Full derived profile and (top) an expansion of the upper 0.1 m of the profile. Data presented include current observations from the polanmetric wave slope sensing method (●) and the moored ADCP (●). Each symbol's fill color corresponds to its direction (deg) clockwise from true north in an oceanographic going-to convention. Wind velocity direction: 321.48°, wind velocity magnitude: 10.99 ms⁻¹; wind stress direction: 326.72°, wind stress magnitude: 0.0175 N m⁻².



Wind Drift Decomposition



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Observation and Estimation of Lagrangian, Stokes, and Eulerian Currents Induced by Wind and Waves at the Sea Surface

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DopplerScatt-HF Radar Sites













Doppler Direction Binning





Wind Direction Binning





Wind Drift Wind Speed Dependence Doppler Directions





Wind Drift Wind Speed Dependence Wind Directions





HF Radar Radial Velocities Doppler Directions





Quantify the role of air-sea Cteraction and surface forcing in the dynamics and vertical

Examine vertical transport processes at submesoscales to mesoscales.



- SMODE: Sub-Mesoscale Ocean Dynamics Experiment
- NASA Earth Ventures Suborbital-3: 2019-2023
- PITom Farrar (WHOI)
- ASIT Tower experiment/WHOI ship experiment (?)



BACKUPS



HF Radar Radial Velocities Wind Directions



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