

# Validation of Scatterometer and Radiometer High Winds Using Oil Platform Anemometers - UPDATE

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# Background

Satellite winds are consistent with buoys for wind speeds < 15 ms<sup>-1</sup>, within a 1 ms<sup>-1</sup> uncertainty.

- Long-standing debate about the validity of buoy winds above 15 ms<sup>-1</sup>.
- RSS satellite winds are 10 15 % higher than buoys (globally) for these wind speeds.
- Verifying the validity of satellite winds between 15-30 ms<sup>-1</sup> is extremely important and can help reconcile a major source of inconsistency between various wind datasets.
- Wind measurements from anemometers mounted on oil platforms in the North Sea provide an important in situ validation source for wind speeds between 15-30 ms<sup>-1</sup>.

# Methodology

- For this study, anemometers underwent rigorous quality control and were compared to satellite and model data.
  - Hourly averaged anemometer wind speeds were collocated with satellite measurements within +/- 1 hour and in the absence of rain.
  - An emometer winds were reduced to a height of 10m using the power law wind profile with  $\alpha \mbox{=} 0.06.$
  - This choice of vertical wind profile is based on work done by Furevik and Haakenstad 2012 and is discussed thoroughly in Manaster et al. 2019\* (published in the Journal of Atmospheric and Ocean Technology in May 2019).



#### Main Conclusions



- Plot shows satellite and model winds minus oil platform anemometer winds in the North and Norwegian Seas for all quality controlled anemometer measurements.
  - Binned vs average wind speed.
  - Model anemometer differences tend to be LARGER than satellite anemometer ones.

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#### Why Do We Trust These Satellite Winds at High Wind Speeds?



Furevik, B. R., and H. Haakenstad, 2012: Near-surface marine wind profiles from rawinsonde and NORA10 hindcast. *J. Geophys. Res.*, 117, D23106, <u>https://doi.org/10.1029/2012JD018523</u>.



#### Error Estimates

- Here we address some issues needed to resolve the debate about the validation of satellite winds with anemometers in the range of 15-30 ms<sup>-1</sup>.
- We analyzed the error budget at moderate and high wind speeds for Windsat quality controlled anemometer observations.
- Many sources of error were taken into account:
  - Atmospheric Stability
  - Ocean Currents
  - Flow Distortion
  - Errors in anemometer measurements themselves
  - Noise (radiometer/scatterometer)
  - RTM/calibration
  - Spatial/temporal sampling mismatch (Representative error. Wentz 1997\*)



### Error Budget 1: Vertical Wind Profile

- Uncertainty in the vertical wind profile due to lack of knowledge of the atmospheric stability at the observation time.
- We have used power law profile with  $\alpha$ =0.06 in order to reference platform winds to 10m.
  - Neutral stability conditions majority of matchups fall in this category.
  - Explored other profiles and other values of  $\alpha$ .
- Range of possible stability conditions leads to error proportional to wind speed.
  - **0.4 ms<sup>-1</sup>** at W = 10 ms<sup>-1</sup> and **0.8 ms<sup>-1</sup>** at W = 22 ms<sup>-1</sup>





## Error Budget 2: Ocean Surface Currents



oceancurrents.rsmas.miami.edu/atlantic/norwegian 2.html

- Neglecting ocean surface currents
- Satellite data = measure wind speeds w.r.t. moving ocean
- Anemometer data = measure wind speeds w.r.t. Earth
- Currents in North and Norwegian seas mostly
  < 0.5 ms<sup>-1</sup>. Rarely higher than 1.0 ms<sup>-1</sup>.
- Since wind generally does not predominantly come from one direction in this area, we treat ocean currents as a random error source and estimate a value of approximately 0.5 ms<sup>-1</sup> for both moderate and high wind speeds.



# Error Budget 3: Flow Distortion

- Possible distortion of the wind field around the oil platform
- Can depend on height and position of the anemometer mounting on the platform.
- Analysis did not reveal any significant bias of quality controlled anemometer measurements w.r.t. wind direction.
- It is difficult to directly estimate other sources of flow distortion, which might lead to positive/negative biases.
  - We do not expect them to be large at high winds.
  - We estimated their uncertainty contribution as a residual from the error budget starting from observed uncertainty.
- Found the upper bounds of possible flow distortion biases were approximately **0.6 ms**<sup>-1</sup> for W = 10 ms<sup>-1</sup> and **1.2 ms**<sup>-1</sup> for W = 22 ms<sup>-1</sup>.





		IV 10 <sup>-1</sup>	TTV 22 -1
	Error source	$W = 10 \text{ m s}^{-1}$	$W = 22 \text{ m s}^{-1}$
1	Platform anemometer	1.25	>1.25
2	Noise (radiometer/ scatterometer)	0.5	0.5
3	RTM/calibration	0.5	0.5
4	Sampling mismatch	0.9	>1.3
5	Atmospheric stability	0.4	0.8
6	Ocean currents	0.5	0.5
7	Flow distortion	< 0.6	<1.2
	Total observed	1.9	2.5

RMS error budget (in ms<sup>-1</sup>) for the Windsat-platform matcups at two different wind speeds (W = 10 ms<sup>-1</sup> and W = 22 ms<sup>-1</sup>). Table 2 from Manaster et al. 2019.

Paper reference: Manaster, A., Ricciardulli, L., and Meissner, T., 2019. Validation of High Ocean Surface Winds from Satellites Using Oil Platform Anemometers. Journal of Atmospheric and Oceanic Technology, 36, 803-818, https://doi.org/10.1175/JTECH-D-18-0116.1.



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# BACKUP SLIDES

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10 2012-2016 WINDSAT-PLATFORM 2003-2011 WINDSAT-PLATFORM AMSR-2-PLATFORM AMSR-E-PLATFORM 5 Sensor-Platform Bias (m/s) -5 **b**). a). -1010-WINDSAT-PLATFORM WINDSAT-PLATFORM 2007-2016 2003-2009 ASCAT-PLATFORM QuikSCAT-PLATFORM 5 -5 **c)**. d -10 -25 4-1-1 - -- - -25 15 20 15 20 10 0 5 10 0 5 Average Sensor/Platform Wind Speed (m/s)

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#### gullfaksc, WIB, Windsat-Platform Bias 2006-2016

