Theory The formulation follows the structure of *Gille et. al.* (2005) and later used by *Tang* et. al. (2014), by modeling the diurnal wind using an elliptical variability, with the addition of the speed-only radiometers, the sub-diurnal terms, the error variance, and the capability to examine each day over the 2003-current period (when at least two scatterometers were jointly operating). Assume we have n wind vector estimates from *n* wind vector-capable satellite passes, all of them during a given day over a given location. This number varies depending upon the time of year, location, and the satellites being considered. The daily and sub-daily u and v components can be expressed with an elliptical fit using a compact matrix formulation: daily sub-daily

$\begin{pmatrix} u_{1} \\ v_{1} \\ \vdots \\ u_{n} \\ v_{n} \\ v_{n} \end{pmatrix} = \begin{pmatrix} a_{0} + a_{1}\cos(2\pi t_{1}/24) + a_{2}\sin(2\pi t_{1}/24) + a_{3}\cos(4\pi t_{1}/24) + a_{4}\sin(4\pi t_{1}/24) \\ b_{0} + b_{1}\cos(2\pi t_{1}/24) + b_{2}\sin(2\pi t_{1}/24) + b_{3}\cos(4\pi t_{1}/24) + b_{4}\sin(4\pi t_{1}/24) \\ \vdots \\ a_{0} + a_{1}\cos(2\pi t_{n}/24) + a_{2}\sin(2\pi t_{n}/24) + a_{3}\cos(4\pi t_{n}/24) + a_{4}\sin(4\pi t_{n}/24) \\ b_{0} + b_{1}\cos(2\pi t_{n}/24) + b_{2}\sin(2\pi t_{n}/24) + b_{3}\cos(4\pi t_{n}/24) + b_{4}\sin(4\pi t_{n}/24) \\ b_{0} + b_{1}\cos(2\pi t_{n}/24) + b_{2}\sin(2\pi t_{n}/24) + b_{3}\cos(4\pi t_{n}/24) + b_{4}\sin(4\pi t_{n}/24) \\ \end{pmatrix}$					
$\begin{vmatrix} v_{1} \\ \vdots \\ u_{n} \\ v_{n} \end{vmatrix} = \begin{vmatrix} b_{0} + b_{1}\cos(2\pi t_{1}/24) + b_{2}\sin(2\pi t_{1}/24) + b_{3}\cos(4\pi t_{1}/24) + b_{4}\sin(4\pi t_{1}/24) \\ \vdots \\ a_{0} + a_{1}\cos(2\pi t_{n}/24) + a_{2}\sin(2\pi t_{n}/24) + a_{3}\cos(4\pi t_{n}/24) + a_{4}\sin(4\pi t_{n}/24) \\ b_{0} + b_{1}\cos(2\pi t_{n}/24) + b_{2}\sin(2\pi t_{n}/24) + b_{3}\cos(4\pi t_{n}/24) + b_{4}\sin(4\pi t_{n}/24) \end{vmatrix}$	$\left(u_{1}^{}\right)$	$\int a_0 + a_1 \cos(2\pi a_0)$	$t_1/24) + a_2 \sin(2\pi t_1)$	$/24) + a_{3}\cos(4\pi t_{1})$	$(24) + a_4 \sin(4\pi t_1 / 24)$
$\begin{vmatrix} \vdots \\ u_n \\ v_n \end{vmatrix} = \begin{vmatrix} \vdots \\ a_0 + a_1 \cos(2\pi t_n/24) + a_2 \sin(2\pi t_n/24) + a_3 \cos(4\pi t_n/24) + a_4 \sin(4\pi t_n/24) \\ b_0 + b_1 \cos(2\pi t_n/24) + b_2 \sin(2\pi t_n/24) + b_3 \cos(4\pi t_n/24) + b_4 \sin(4\pi t_n/24) \end{vmatrix}$	<i>v</i> ₁	$b_0 + b_1 \cos(2\pi t)$	$t_1/24) + b_2 \sin(2\pi t_1)$	$/24) + b_{3}\cos(4\pi t_{1})$	$(24) + b_4 \sin(4\pi t_1 / 24)$
$\begin{bmatrix} u_n \\ v_n \end{bmatrix} \begin{bmatrix} a_0 + a_1 \cos(2\pi t_n/24) + a_2 \sin(2\pi t_n/24) + a_3 \cos(4\pi t_n/24) + a_4 \sin(4\pi t_n/24) \\ b_0 + b_1 \cos(2\pi t_n/24) + b_2 \sin(2\pi t_n/24) + b_3 \cos(4\pi t_n/24) + b_4 \sin(4\pi t_n/24) \end{bmatrix}$: =	:	:	•	•
$\left(v_{n} \right) \left(b_{0} + b_{1} \cos(2\pi t_{n}/24) + b_{2} \sin(2\pi t_{n}/24) + b_{3} \cos(4\pi t_{n}/24) + b_{4} \sin(4\pi t_{n}/24) \right)$	u_n	$a_0 + a_1 \cos(2\pi a_0)$	$t_n/24) + a_2 \sin(2\pi t_n)$	$/24) + a_{3}\cos(4\pi t_{n})$	$(24) + a_4 \sin(4\pi t_n / 24)$
	$\left(v_{n} \right)$	$b_0 + b_1 \cos(2\pi t)$	$t_n/24) + b_2 \sin(2\pi t_n)$	$/24) + b_3 \cos(4\pi t_n)$	$(24) + b_4 \sin(4\pi t_n / 24)$

	1	$\cos(2\pi t_1^2/24)$	$\sin(2\pi t_1^2/24)$	$\cos(4\pi t_1^2/24)$	$\cos(4\pi t_1/24)$	$\vec{x} = (a_0 a_1 a_2 a_2 a_3)$
$\begin{bmatrix} A \end{bmatrix} =$	1	$\vdots \qquad \vdots \qquad$	$\frac{1}{2} \sin(2\pi t / 2A)$	$\vdots \qquad \vdots \qquad$	\vdots	$\vec{v} = (b \ b \ b \ b \ b \ b \ b \ b \ b \ b $
l		$\cos(2\pi t_n/24)$	$\operatorname{SIII}(2\pi n_n/24)$	$\cos(4\pi t_n/24)$	$\cos(4\pi t_n/24)$	$\int (v_0 v_1 v_2 v_3 v_4)$

$$\vec{x} = \left(A^{T} D_{u}^{-1} A\right)^{-1} A^{T} D_{u}^{-1} U$$

$$\vec{y} = \left(A^{T} D_{v}^{-1} A\right)^{-1} A^{T} D_{v}^{-1} V$$

In either case, these expressions can be expressed in matrix form, where D_{μ} and D_{v} are diagonal matrices with the variance of the *u* and *v* observations.

For the speed-only (w) radiometers, since the relation between w and the u and v components is non-linear, hypothetical vectors are created by varying the directions one degree at a time (e.g., for one radiometer):

 $u_{n+1} = w\cos(\theta) = a_0 + a_1\cos(2\pi t_1/24) + a_2\sin(2\pi t_1/24) + a_3\cos(4\pi t_1/24) + a_4\cos(4\pi t_1/24)$ $v_{n+1} = w\sin(\theta) = b_0 + b_1\cos(2\pi t_1/24) + b_2\sin(2\pi t_1/24) + b_3\cos(4\pi t_1/24) + b_4\cos(4\pi t_1/24)$

$$E(\theta) = \min\left(\sum_{i=1}^{n} (u_{n+1} - u_i)^2 + (v_{n+1} - v_i)^2\right)$$

And locating the directions θ that best agree with the observed vectors.

Referencing to Common Sensor

It is important to adjust the multiple wind datasets relative to a "reference" sensor, prior to joint analysis for geophysical patterns. In this study, the asynchronous orbiting TRMM-TMI V7 0.25-degree wind speed products are used as the reference from 1999-2014, and GPM-GMI from April 2014-current, both produced by RSS (eight-month overlap period between TMI and GMI). Per-pixel coincidences within ±5-min between TMI (or GMI) and each of the 15 other different wind speed or wind vector (depending upon sensor type) datasets were collected over the Nov 1999-Mar 2016 period. Bias correction lookup tables were generated for each 0.5 m/s wind speed bin of the reference sensor. These were applied to adjust each of the non-reference sensors, prior to any qualitative analysis. For purposes of this presentation, a single bias adjustment table was generated from all 15 non-reference datasets.

1999-2016 ±5-min Coincidences With TRMM-TMI or GPM-GMI **16 Different Wind or Wind Vector Datasets**



Gille, S.T., et. al. (2005). Global observations of the land breeze. Geophys. Res. Letters, 32. Tang, W., et. al. (2014). Detection of diurnal cycle of ocean surface wind from space-based observations. *Int*. J. Rem. Sens., 35, 5328-5341.





Examining the Constellation of Scatterometers and Radiometers for Diurnal and Sub-Diurnal Wind Vector Variability



The constellation of satellite-based ocean surface wind and precipitation observations since 1999 consists of a diverse collection of both sun-synchronous and asynchronous orbiting satellite platforms, both wind vector-capable (RapidScat, QuikSCAT, SeaWinds, ASCAT, OceanSat2, WindSat, RapidScat) and speedonly radiometers (TMI, GMI, AMSR, AMSR-2, SSMIS). These data can be jointly examined for time-of-day variability over regions where the surface wind varies widely throughout the day, owing to various meteorological forcings, such as land/sea temperature differences near coasts, or possible variations associated with tropical convective precipitation. Early results of an analysis are described whereby multiple wind speed and wind vector products were jointly examined to investigate the diurnal (and semidiurnal, in cases) ocean wind vector variability.







All radiometers, WindSat and ASCAT (V2) wind datasets were obtained from Remote Sensing Systems, Inc., (RSS) and who are gratefully acknowledged. QuikSCAT, ASCAT, RapidScat and SeaWinds data were obtained from the Physical Oceanography Distributed Active Archive (PO.DAAC). The authors acknowledge support from the NASA OVW science team. This work was carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with NASA.

Thirteen-Year Analysis

The maps on the left show mean values over limited 7-month periods. To examine the day-to-day variability over a long term, all products listed on the left side were examined for the entire April 2003-Feb 2016 period, over specific "target areas" where the major axis exceed 2 m s⁻¹. Both the daily-only (three **a** and three **b** coefficients estimated for each day), and daily+sub-daily analysis (five **a** and five **b** coefficients estimated for each day) was done, to examine the the persistence of the daily-only variability, and to further analyze for the presence of any sub-daily variability. Days are included only when the magnitude of the diurnal u and v components sufficiently exceeded the variability (twice the standard deviation) in the estimated regression coefficient terms.

AMSR-2 direction (deg)

AMSR-2 direction (deg)

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