

Developing Accuracy Constraints for Climate Quality Observations



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Many Air/Sea Interaction Processes - Most are strongly influenced by wind (or stress) -





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Scatterometry and Climate Workshop 2



Coupling Fluxes at the Air/Sea Interface

- How accurately do we have to know the various fluxes through the air sea interface?
 - Stress vertical transport of horizontal momentum (Nm⁻²)
 - Magnitude proportional to wind speed squared or cubed
 - Latent heat heat transferred through phase change from water to water vapor (Js⁻¹m⁻² = Wm⁻²)
 - Proportional to wind speed & air/sea moisture difference
 - Sensible heat heat transferred without phase change from water to air $(Js^{-1}m^{-2} = Wm^{-2})$
 - Proportional to wind speed & air/sea temperature difference
 - Evaporation proportional to latent heat flux $(kgs^{-1}m^{-2})$
 - Proportional to wind speed & air/sea moisture difference
 - Precipitation rain of snow falling and reaching the surface
- The curl of the stress is very important for vertical motion and deep circulation.





Flux and Wind Accuracies Desired for Various Applications



Observational Errors

- Errors can be described as composed of
 - A bias (this bias could be a function of environmental conditions),
 - Random uncertainty, and
 - More complicated systematic errors
- We are primarily interested in how biases in observations of wind speed (w)
 - sea surface temperature (SST), near surface air temperature (T_{air}) , and near surface humidity (q_{air}) translate to biases in calculated fluxes.
 - Turbulent fluxes: sensible heat (H), latent heat (L), and stress (τ) .
- In general, the bias in one of these observations can be related to the bias in a flux through a Sensitivity (S).
- Symmetrically distributed random errors in data that are used linearly will cause only small error if there is a large enough sample.
 - Non-linear processes can result in biases due to random errors.





Biases – For Specific Conditions

- Example: How much does a bias in speed (Δw) contribute to a bias in the latent heat flux (ΔL)?
 - $\Delta L = S_{L,w} \Delta w$
 - If S_{L,w} is very large, then even a small bias in w can result in a large bias in L.
 - If the sensitivity is very small, then the calculated variable is insensitive to errors in the observation.
- The maximum allowable bias in an observation (e.g., $|\Delta w|$) can be estimated from the maximum specified error in the calculated variable (e.g., $|\Delta L|_{max}$), and the sensitivity (e.g., $S_{L,w}$)
 - $|\Delta w|_{max} = |\Delta L|_{max} / |S_{L,w}|$
- The sensitivity is the partial derivative of the output quantity (e.g., the flux) with respect to the input observation (e.g., wind speed).

•
$$S_{L,w} = \partial L / \partial w$$









Example: Sensitivity of Latent Heat Flux to Errors in Wind Speed: ∂(E/∆q)/∂w



Error Limits for Observation Errors

- For this talk, we will ignore random errors, assuming that they will be small given enough samples.
 - This is a common assumption, but will not be true for all applications!
- The maximum allowable bias in an observation (e.g., $|\Delta w|$) can be estimated from the maximum specified error in the calculated variable (e.g., $|\Delta E|$), and the sensitivity (e.g., $S_{E,w}$)
 - $|\Delta w|_{max} = |\Delta E|_{max} / |S_{E,w}|$









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Conclusions

• Speed constraints

- For *average* open ocean conditions, accuracy requirements for turbulent heat fluxes are easily achieved: ~1ms⁻¹ bias is OK.
 - Might be OK for tropics for annual applications
 - Insufficient for mid-latitudes
- For harsh mid-latitude conditions, speed biases of $\leq 0.2 \text{ms}^{-1}$ are needed
- For multi-decadal applications slightly finer accuracy is needed.
- Direction
 - While direction is very important for physical processes, the bias constraints for direction (or vector component error) are not known.
 - Slightly finer accuracy might be needed for Sverdrup flow?
- There are applications that are non-linearly dependent on wind speed (or stress) for which the impacts of random errors should be investigated.
- Sampling of the synoptic and diurnal variability could also cause biases.



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Surface Turbulent Fluxes and Scatterometry



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Suggested Measurement Accuracy For Research Vessels

Table 1: Accuracy, precision and random error targets for SAMOS. Accuracy estimates are currently based on time scales for climate studies (i.e., $\pm 10 \text{ W/m}^2$ for Q_{net} on monthly to seasonal timescales). Several targets are still to be determined.

	Accuracy of Mean	Data	Random Error
Parameter	(bias)	Precision	(uncertainty)
Latitude and	0.001°	0.001°	
Longitude			
Heading	2°	0.1°	
Course over	2°	0.1°	
ground			
Speed over ground	Larger of 2% or 0.2 m/s	0.1 m/s	Greater of 10% or 0.5 m/s
Speed over water	Larger of 2% or 0.2 m/s	0.1 m/s	Greater of 10% or 0.5 m/s
Wind direction	3°	1°	
Wind speed	Larger of 2% or 0.2 m/s	0.1 m/s	Greater of 10% or 0.5 m/s
Atmospheric	0.1 hPa (mb)	0.01 hPa	
Pressure		(mb)	
Air Temperature	0.2 °C	0.05 °C	
Dewpoint	0.2 °C	0.1 °C	
Temperature			
Wet-bulb	0.2 °C	0.1 °C	
Temperature			
Relative Humidity	2%	0.5 %	
Specific Humidity	0.3 g/kg	0.1 g/kg	
Precipitation	~0.4 mm/day	0.25 mm	
Radiation (SW in,	5 W/m^2	1 W/m^2	
LW in)			
Sea Temperature	0.1 °C	0.05 °C	
Salinity			
Surface Current	0.1 m/s	0.05 m/s	

I will assume that a 5Wm⁻² is the limit for biases in radiative fluxes.

• Then 5Wm⁻² is the limit for biases in surface turbulent heat fluxes.





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Curl of the Stress



Standard Deviation of the Curl of the Stress



Drag Coefficient vs. Wind Speed



- Preliminary data form the SWS2 (Severe Wind Storms 2) experiment.
 - The drag coefficients for high wind speeds are large and plentiful.
 - The atypically large drag coefficients are associated with rising seas
- Many models underestimate these fluxes.
- Spread is much bigger than expected from observational errors





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How Do Waves Enter The Picture?

• The surface turbulent stress and LHF are usually parameterized as

$$\tau = \rho C_D U_{10}^2 \qquad \qquad L = \rho L_v C_E (q_{10} - q_{\rm sfc}) U_{10}$$

• This form can be more accurately written as

$$\boldsymbol{\tau} = \rho C_{D} \left| \mathbf{U}_{10} \right| \mathbf{U}_{10} \qquad \qquad \boldsymbol{L} = \boldsymbol{\rho} L_{v} C_{E} \left(\boldsymbol{q}_{10} - \boldsymbol{q}_{sfc} \right) \left| \mathbf{U}_{10} \right|$$

• It can be further improved in terms of surface relative wind vectors:

$$\boldsymbol{\tau} = \rho C_{D} \left| \mathbf{U}_{10} - \mathbf{U}_{sfc} \right| \left(\mathbf{U}_{10} - \mathbf{U}_{sfc} \right) \qquad L = \rho L_{v} C_{E} \left(q_{10} - q_{sfc} \right) \left| \mathbf{U}_{10} - \mathbf{U}_{sfc} \right|$$

- Does a scatterometer respond to \mathbf{U}_{10} or to $\mathbf{U}_{10} \mathbf{U}_{sfc}$?
 - *Cornillon and Park* (2001, *GRL*), *Kelly et al.* (2001, *GRL*), and *Chelton et al.* (2004, *Science*) showed that scatterometer winds were relative to surface currents.
 - *Bentamy et al.* (2001, *JTech*) indicate there is also a dependence on wave characteristics.
 - *Bourassa* (2006, *WIT Press*) showed that wave dependency can be parameterized as a change in U_{sfc} .



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Ocean's TKE Based on Observed Surface Fluxes





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